

COSC 2011 Section N

Tuesday, May 8 2001

Overview

- Undirected Graph Traversals
 - ◆ Depth-First Search
 - ◆ Breadth-First Search

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Undirected Graph Traversal - DFS:

- Definition:
 - ◆ A *graph traversal* is a systematic procedure for visiting all vertices and edges of a graph.
 - ◆ Efficient if it visits all vertices and edges in linear time.
 - ◆ Two efficient methods:
 - ★ Depth-First Search
 - ★ Breadth-First Search

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Undirected Graph Traversal - DFS:

- Depth-First Search (DFS):
 - ◆ “Search” deeper in the graph whenever possible.
 - ◆ Edges are “explored” out of the the most recently visited vertex v that still has unexplored edges leaving it.
 - ◆ When all of v 's edges have been explored, search “backtracks” to

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Undirected Graph Traversal - DFS:

- ◆ explore edges leaving the vertex from which v was discovered.
- ◆ This process continues until all vertices reachable from the original source vertex have been discovered.
- ◆ If any undiscovered vertices remain, one of them is selected as a new source and search repeats.

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Exploring a Labyrinth Without Getting Lost

- A **depth-first search (DFS)** in an undirected graph G is like wandering in a labyrinth with a string and a can of red paint without getting lost.
- We start at vertex s , tying the end of our string to the point and painting s "visited". Next we label s as our current vertex called u .
- Now we travel along an arbitrary edge (u,v) .
- If edge (u,v) leads us to an already visited vertex v we return to u .
- If vertex v is unvisited, we unroll our string and move to v , paint v "visited", set v as our current vertex, and repeat the previous steps.
- Eventually, we will get to a point where all incident edges on u lead to visited vertices. We then backtrack by unrolling our string to a previously visited vertex w . Then w becomes our current vertex and we repeat the previous steps.

Depth-First Search

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Exploring a Labyrinth Without Getting Lost (cont.)

- Then, if all incident edges on v lead to visited vertices, we backtrack as we did before. We continue to backtrack along the path we have traveled, finding and exploring unexplored edges, and repeating the procedure.
- When we backtrack to vertex s and there are no more unexplored edges incident on s , we have finished our **DFS** search.

Depth-First Search

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Undirected Graph Traversal - DFS:

- Visualize DFS by orienting edges along the directions they are explored during the traversal.
 - ◆ **Discovery** or **tree** Edges:
 - ★ Edges used to discover new vertices.
 - ◆ **Back** Edges:
 - ★ Edges leading to already visited vertices.

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Undirected Graph Traversal - DFS:

- ◆ Discovery edges form a **spanning tree** of the connected component starting at start vertex s .

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Undirected Graph Traversal - DFS:

■ Algorithm:

Algorithm DFS(v):

Input: A vertex v in a graph

Output: A labeling of the edges as "discovery" edges and "backedges"

for each edge e incident on v **do**

if edge e is unexplored **then**

 let w be the other endpoint of e

if vertex w is unexplored **then**

 label e as a discovery edge

 recursively call **DFS**(w)

else

 label e as a backedge

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Undirected Graph Traversal - DFS:

■ Algorithm Assumptions:

- ◆ Have a "way" to determine whether a vertex or edge has been explored or not.
- ◆ Have a "way" to label edges as discovery or back edges.
- ◆ This may require additional storage space and may affect running time!

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DFS Properties

• Proposition 9.12: Let G be an undirected graph on which a **DFS** traversal starting at a vertex s has been performed. Then:

- 1) The traversal visits all vertices in the connected component of s
- 2) The discovery edges form a spanning tree of the connected component of s

• Justification of 1):

- Let's use a contradiction argument: suppose there is at least one vertex v not visited and let w be the first unvisited vertex on some path from s to v .
- Because w was the first unvisited vertex on the path, there is a neighbor u that has been visited.
- But when we visited u we must have looked at edge (u, w) . Therefore w must have been visited.
- and justification

• Justification of 2):

- We only mark edges from when we go to unvisited vertices. So we never form a cycle of discovery edges, i.e. discovery edges form a tree.
- This is a spanning tree because **DFS** visits each vertex in the connected component of s

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Undirected Graph Traversal - DFS:

■ Running Time:

• Remember:

- **DFS** is called on each vertex exactly once.
- Every edge is examined exactly twice, once from each of its vertices
- For n_s vertices and m_s edges in the connected component of the vertex s , a **DFS** starting at s runs in $O(n_s + m_s)$ time if:
 - The graph is represented in a data structure, like the adjacency list, where vertex and edge methods take constant time
 - Marking a vertex as explored and testing to see if a vertex has been explored takes $O(\text{degree})$
 - By marking visited nodes, we can systematically consider the edges incident on the current vertex so we do not examine the same edge more than once.

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Undirected Graph Traversal - DFS:

Marking Vertices

- Let's look at ways to mark vertices in a way that satisfies the above condition.
- Extend vertex positions to store a variable for marking



- Use a hash table mechanism which satisfies the above condition in the probabilistic sense, because it supports the mark and test operations in $O(1)$ expected time

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Undirected Graph Traversal - DFS:

- Let G be a graph with n vertices and m edges represented with an adjacency list structure. There exists $O(n+m)$ algorithms based on DFS to compute:
 - ◆ Test whether G is connected.
 - ◆ Compute *spanning tree* of G if G is connected.
 - ◆ Compute connected components of G .
 - ◆ Compute path between two vertices of G or report no path such path exists.
 - ◆ Compute cycle in G or report no cycle exists.

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DFS Example: (1)

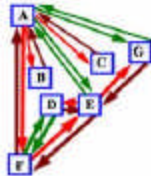
Determining Incident Edges

- DFS depends on how you obtain the incident edges.
- If we start at A and we examine the edge to F , then to B , then E , C , and finally G



The resulting graph is:

- discoveryEdge
- backEdge
- return from dead end



If we instead examine the tree starting at A and looking at F , then C , then E , B , and finally F .



the resulting set of backEdges, discoveryEdges and recursion points is different.

- Now an example of a DFS.

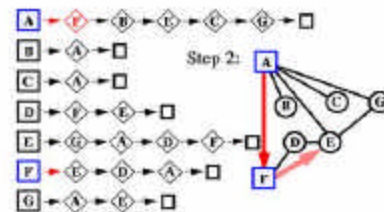
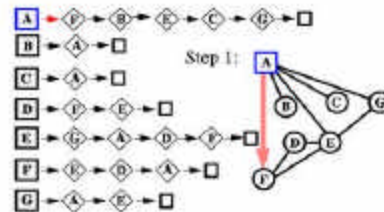
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DFS Example: (2)



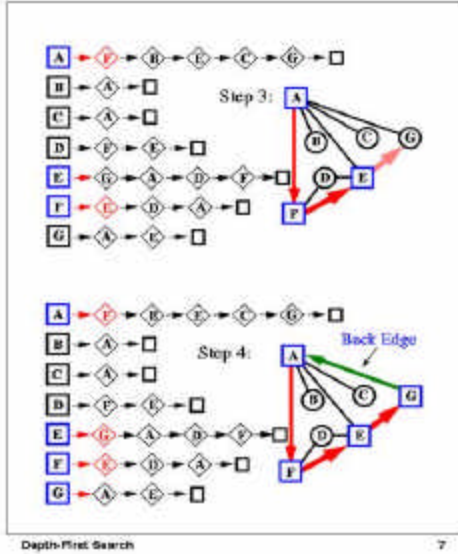
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DFS Example: (3)

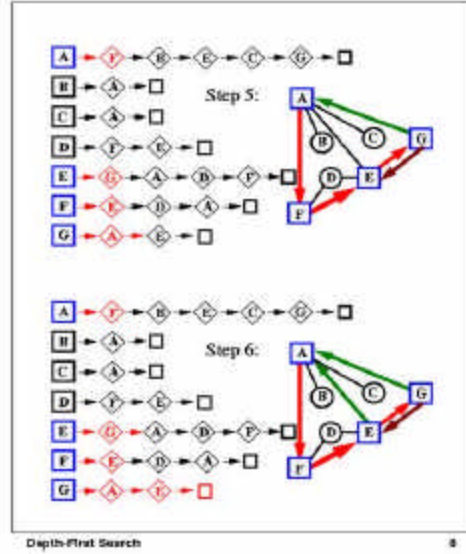


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DFS Example: (4)

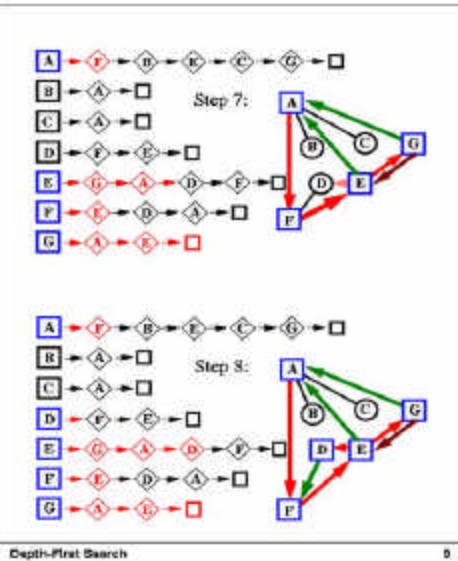


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DFS Example: (5)

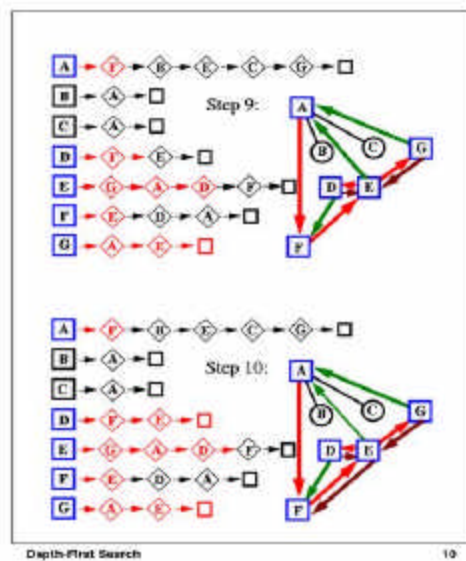


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DFS Example: (6)

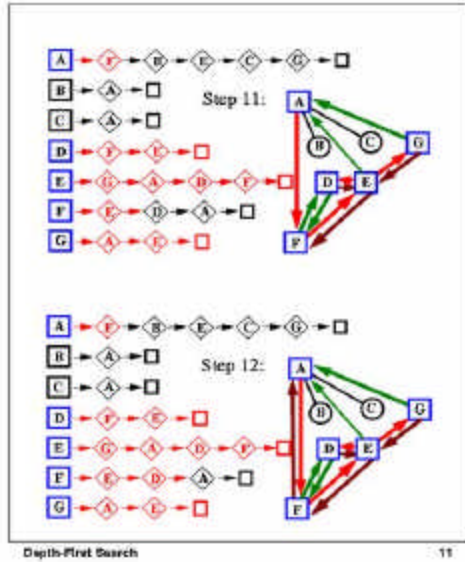


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DFS Example: (7)

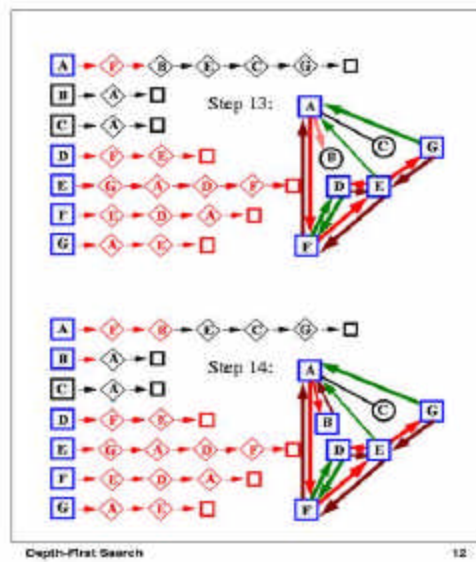


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DFS Example: (8)

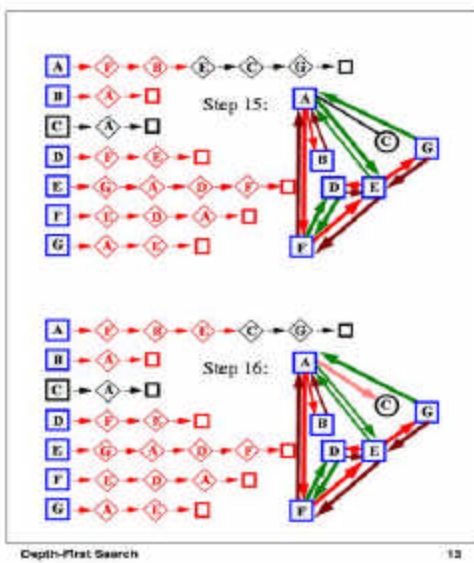


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DFS Example: (9)

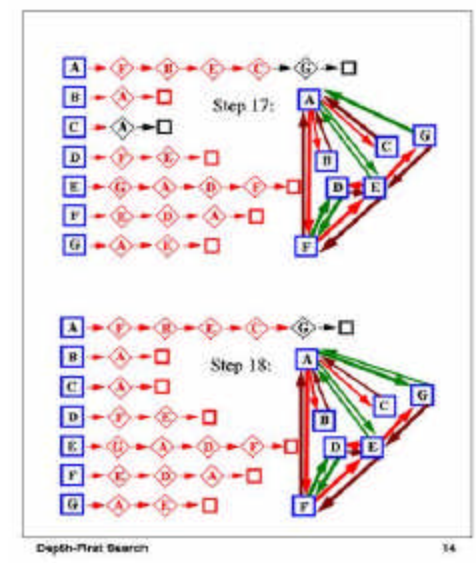


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DFS Example: (10)

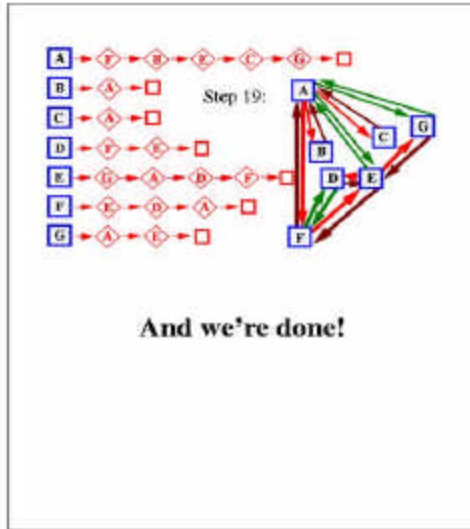


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DFS Example: (11)



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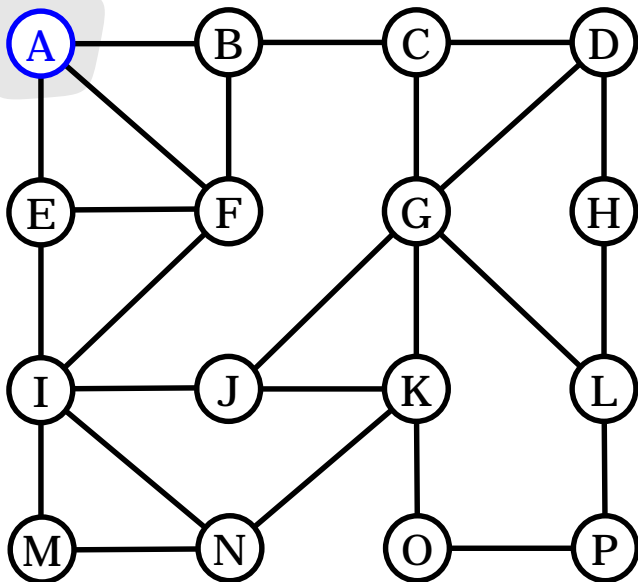
Breadth-First Search

- Like **DFS**, a **Breadth-First Search (BFS)** traverses a connected component of a graph, and in doing so defines a spanning tree with several useful properties
 - The starting vertex s has level 0, and, as in **DFS**, defines that point as an “anchor.”
 - In the first round, the string is unrolled the length of one edge, and all of the edges that are only one edge away from the anchor are visited.
 - These edges are placed into level 1
 - In the second round, all the new edges that can be reached by unrolling the string 2 edges are visited and placed in level 2.
 - This continues until every vertex has been assigned a level.
 - The label of any vertex v corresponds to the length of the shortest path from s to v .

BFS - A Graphical Representation

a)

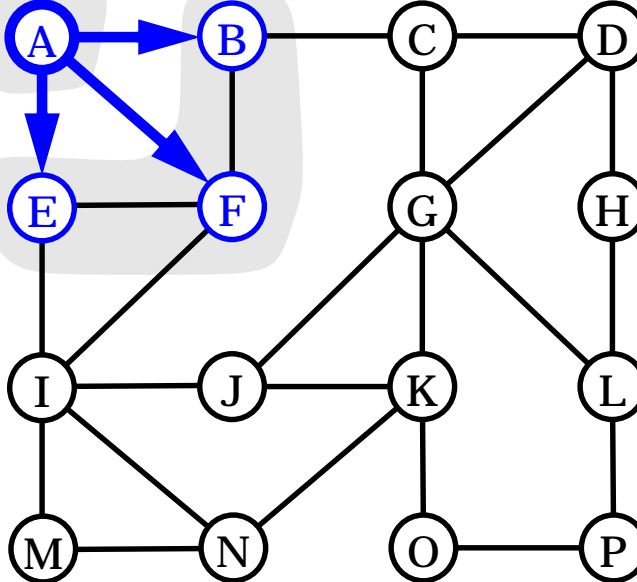
0



b)

0

1

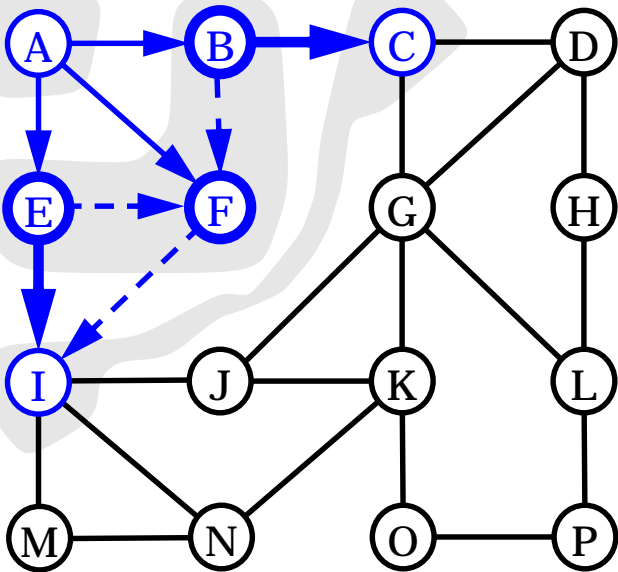


c)

0

1

2



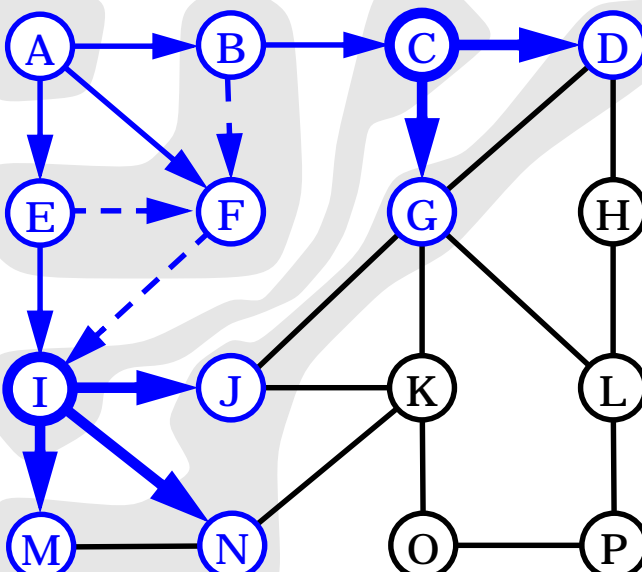
d)

0

1

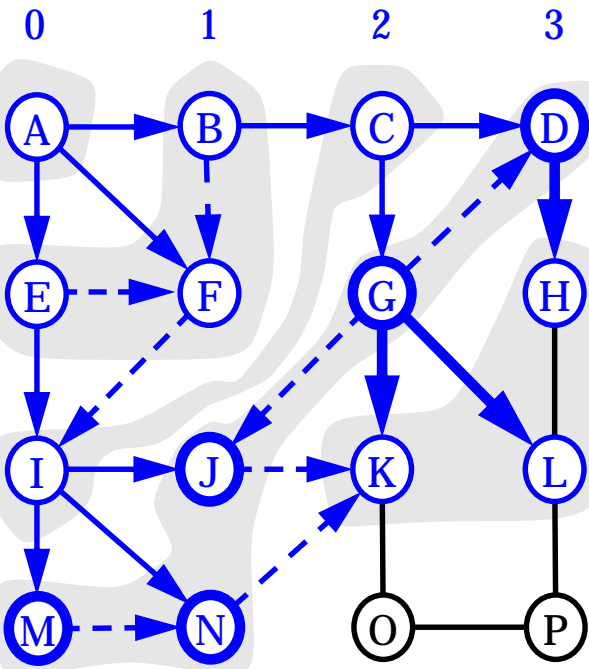
2

3

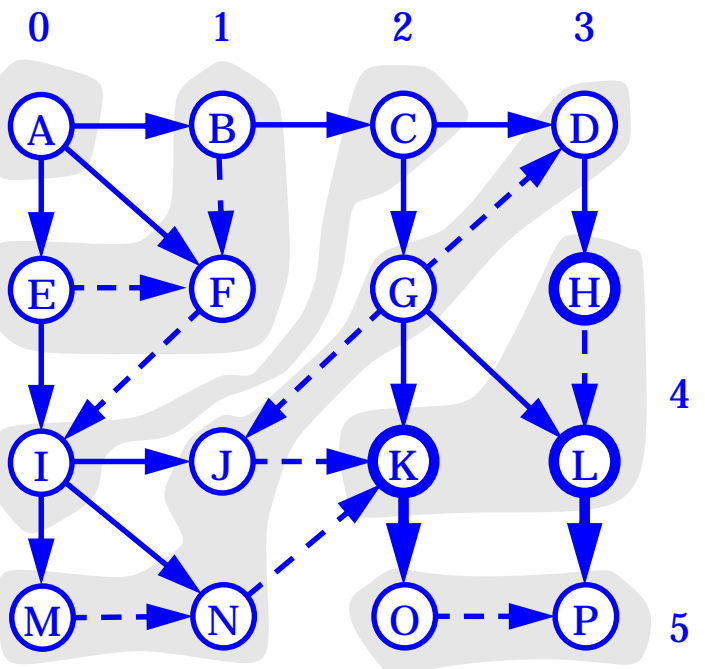


More BFS

e)



f)



BFS Pseudo-Code

Algorithm **BFS**(s):

Input: A vertex s in a graph

Output: A labeling of the edges as “discovery” edges
and “cross edges”

initialize container L_0 to contain vertex s

$i \leftarrow 0$

while L_i is not empty **do**

 create container L_{i+1} to initially be empty

for each vertex v in L_i **do**

for each edge e incident on v **do**

if edge e is unexplored **then**

 let w be the other endpoint of e

if vertex w is unexplored **then**

 label e as a discovery edge

 insert w into L_{i+1}

else

 label e as a cross edge

$i \leftarrow i + 1$

Properties of BFS

- **Proposition:** Let G be an undirected graph on which a **BFS** traversal starting at vertex s has been performed. Then
 - The traversal visits all vertices in the connected component of s .
 - The discovery-edges form a spanning tree T , which we call the **BFS** tree, of the connected component of s
 - For each vertex v at level i , the path of the **BFS** tree T between s and v has i edges, and any other path of G between s and v has at least i edges.
 - If (u, v) is an edge that is not in the **BFS** tree, then the level numbers of u and v differ by at most one.
- **Proposition:** Let G be a graph with n vertices and m edges. A **BFS** traversal of G takes time $O(n + m)$. Also, there exist $O(n + m)$ time algorithms based on BFS for the following problems:
 - Testing whether G is connected.
 - Computing a spanning tree of G
 - Computing the connected components of G
 - Computing, for every vertex v of G , the minimum number of edges of any path between s and v .